## DIFFERENTIAL PRESSURE TRANSMITTER TYPE PDR-IE



## DESCRIPTION

PDR-IE is a combination of differential pressure sensor based on variable reluctance and the signal conditioner ICAB consisting of an excitation oscillator, a true differential input amplifier, a phase sensitive demodulator, a low-pass filter and an output stage. The output signal can be configured by the user through the jumpers on top of the PCB. All connections are transient protected and a metal shield box covering all sensitive components ensures high electromagnetic compatibility. The electronics is mounted in an Al-box (IP65) on top of the sensor.

SPECIFICATIONS

| Standard ranges | $\begin{aligned} & \pm 50 \mathrm{mbar}, \pm 100 \mathrm{mbar}, \pm 200 \mathrm{mbar}, \pm 500 \mathrm{mbar}, \\ & \pm 1 \mathrm{bar}, \pm 2 \mathrm{bar}, \pm 5 \mathrm{bar} \text { and } \pm 10 \mathrm{bar} \end{aligned}$ |
| :---: | :---: |
| Non-linearity and hysteresis | < $\pm 0.5$ \% |
| Overpressure | 200\% FS with less than $0.5 \%$ zero shift. |
| Line pressure | 200 bar max. less than 1,5\% FS zero shift/100bar |
| Pressure media | Corrosive liquids and gasses both sides, compatible with AISI 410 ( Werkstoff-Nr 1.4006 ) |
| Output signals <br> - AIA1 <br> - B/B1 <br> - BA/BA1 <br> - C/C1 <br> - D1 (D-configuration not available) | Selected by jumpers beside the terminals 4-20 mA $A_{D C}, 2$-wire, $R_{L}$ : see diagram, $C_{L}<1 \mu F$. $0-20 \mathrm{~mA}_{\mathrm{DC}}, 3$-wire, $\mathrm{R}_{\mathrm{L}}<700 \Omega, \mathrm{C}_{\mathrm{L}}<1 \mu \mathrm{~F}$ 4-20 mA ${ }_{D C}$, 3 -wire, $\mathrm{R}_{\mathrm{L}}<700 \Omega, \mathrm{C}_{\mathrm{L}}<1 \mu \mathrm{~F}$ $0-5 \mathrm{~V}_{\mathrm{DC}}, 4$-wire, $\mathrm{R}_{\mathrm{L}}>5 \mathrm{k} \Omega, \mathrm{C}_{\mathrm{L}}<1 \mu \mathrm{~F}$ <br> $\pm 2.5 \mathrm{~V}_{\mathrm{DC}}, 4$-wire, $\mathrm{R}_{\mathrm{L}}>20 \mathrm{k} \Omega, \mathrm{C}_{\mathrm{L}}<1 \mu \mathrm{~F}$ |
| Power requirement | $12-30 \mathrm{~V}_{D C}, 4 \mathrm{~mA} \mathrm{~A}_{\mathrm{DC}}+$ output signal current |
| Supply voltage rejection | min. 86 dB between 12 and $30 \mathrm{~V}_{\mathrm{DC}}$ |
| Response time (0-100 \%) | 6 msec |
| Output signal ripple | <0,05 \% p-p of FSO |
| GAIN adjustment | $\pm 10 \%$ of FSO |
| PHASE adjustment | 0-180 degrees. |
| BALANCE adjustment | $\pm 10 \%$ of FSO |
| Temperature range | $-25^{\circ} \mathrm{C}$ to $+85{ }^{\circ} \mathrm{C}$ (media must not freeze) |
| Temperature coefficient | $<0.07 \% /{ }^{\circ} \mathrm{C}$ of FSO |
| Pressure connections | G $1 / 4$ " |
| Electrical connections | Screw terminals max. $1.5 \mathrm{~mm}^{2}$, cable diameter 5 to 10 mm |
| Environmental conditions <br> - electromagnetic immunity <br> - electromagnetic emission | According to EN 50082-2 (generic industrial standard) <br> According to EN 50081-2 (generic industrial standard) |
| Weight | 0.75 kg |
| Protection class | IP65 |

## INSTALLATION

Mount the transmitter directly to a base. Remove the protection caps and connect pressure supplies to the pressure ports. Bleeding screws allows complete liquid filling for dynamic measurements. Check the jumper setting according to the application and connect the transmitter following the External Connections diagram. Use only shielded cables for connection. The cable shield should be connected both inside the cable gland of the transmitter and to the EMC-reference of the associated electronics.

## ADJUSTMENT

The transmitter is factory calibrated with reference to the requested output signal and type sign, and followed by a Certificate of Accuracy. Calibration should be checked after service performed by the user or according to a user maintenance procedure. The output signal can be changed by moving the jumpers on the PCB. Calibration is within $2 \%$. To recalibrate, let sensor be depressurized. With jumper setting GAIN=1: BALANCE to the $50 \%$ output signal value ( $0 \mathrm{~V}_{\mathrm{DC}}$ in the D1-configuration) or with GAIN=2: BALANCE to the $0 \%$ output signal value. Apply FS pressure and adjust to largest output with PHASE. Adjust to $100 \%$ output signal value with GAIN. Check output with sensor in minimum state and repeat if necessary. A new offset is adjusted with BALANCE.

## ORDERING INFORMATION

| " x " | AlBA | A1/BA1 | B | B1 | C | C1 | D1 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| SETUP | GAIN $=2$ | GAIN $=1$ | GAIN=2 | GAIN $=1$ | GAIN $=2$ | GAIN $=1$ | GAIN $=1$ |
| -FS |  | 4 mA |  | 0 mA |  | 0 V | -2.5 V |
| 0 bar | 4 mA | 12 mA | 0 mA | 10 mA | 0 V | 2.5 V | 0 V |
| +FS | 20 mA | 20 mA | 20 mA | 20 mA | 5 V | 5 V | +2.5 V |

