## EPA300 UNIVERSAL PROCESS CONTROLLER MODBUS PROTOCOL ADDRESS TABLES

## **COIL ADDRESS TABLE**

Coil Address(hex)	Parameter Name	Parameter Explanation	Count of Bit	Value	Read/Write
0x00	RESET_VALLEY	Resetting the minimum value read since the device was started		Default Value = 0 0 = Inactive 1 = Active	Read/Write
0x01	RESET_PEAK	Resetting the maximum value read since the device was started	]		
0x02	RESET_PEAK_VALLEY	Resetting the maximum and minimum values read since the device was started			
0x03	TARE_APPLY	Activating the Tare function			
0x04	PLAY_BUZZER_100MS	Buzzer's beeping	1 bit		
0x05	OUT1_SET	Switch off the relay 1			
0x06	OUT1_CLEAR	Switch on the relay 1			
0x07	OUT2_SET	Switch off the relay 2			
0x08	OUT2_CLEAR	Switch on the relay 2			
0x09	OUT3_SET	Switch off the relay 3			
0x0A	OUT3_CLEAR	Switch on the relay 3			
0x0B	OUT4_SET	Switch off the relay 4			
0x0C	OUT4_CLEAR	Switch on the relay 4			

<sup>\*</sup>In order for the relay outputs to be controlled by the coil parameters, the corresponding relay (mode) must be OFF.

## **HOLDING REGISTER ADDRESS TABLE**

	ding Register Idress (hex)	Parameter Name	Parameter Explanation	Count of Bit	Default Value	Read/Write
	0x00	DECIMAL_POINTS	Decimal point location on the screen display (0=A, 1=A.A, 2=A.AA, 3=A.AAA 4=A.AAAA)	16 bit (word)	1	Read/Write
	0x01	SET1A_HIGH	Set-1A value [MSB]	16 bit (H word)	0	
	0x02	SET1A_LOW	Set-1A value [LSB]	16 bit (L word)	250	
	0x03	SET1B_HIGH	Set-1B value [MSB]	16 bit (H word)	0	
	0x04	SET1B_LOW	Set-1B value [LSB]	16 bit (L word)	350	
t	0x05	MODE1	Function type (0=OFF, 1=Stand, 2=Band, 3=Catch, 4=Dual, 5=Periodic)	16 bit (word)	1	Dood Mysics
Output	0x06	DELAY1_HIGH	Delay time (second) [MSB]	16 bit (H word)	0	
	0x07	DELAY1_LOW	Delay time (second) [LSB]	16 bit (L word)	0	
ıy 1	0x08	HYSUP1_HIGH	Upper hysteresis value [MSB]	16 bit (H word)	0	Read/Write
Relay	0x09	HYSUP1_LOW	Upper hysteresis value [LSB]	16 bit (L word)	0	
	0x0A	HYSDOWN1_HIGH	Lower hysteresis value [MSB]	16 bit (H word)	0	
	0x0B	HYSDOWN1_LOW	Lower hysteresis value [LSB]	16 bit (L word)	0	
	0x0C	OFFSET1_HIGH	Offset value [MSB]	16 bit (H word)	0	
	0x0D	OFFSET1_LOW	Offset value [LSB]	16 bit (L word)	0	
	0x0E	CONDITION_MODE1	Normally the state of the relay (0 = N.C. = Off 1 = N.O. = On)	16 bit (word)	0	

		н	OLDING REGISTER ADDRESS TAE	BLE		
	ding Register Idress (hex)	Parameter Name	Parameter Explanation	Count of Bit	Default Value	Read/Write
	0x0F	SET2A_HIGH	Set-2A value [MSB]	16 bit (H word)	0	
	0x10	SET2A_LOW	Set-2A value [LSB]	16 bit (L word)	350	1
	0x11	SET2B_HIGH	Set-2B value [MSB]	16 bit (H word)	0	
	0x12	SET2B_LOW	Set-2B value [LSB]	16 bit (L word)	500	
ut	0x13	MODE2	Function type (0=OFF, 1=Stand, 2=Band, 3=Catch, 4=Dual, 5=Periodic)	16 bit (word)	1	
Relay 2 Output	0x14	DELAY2_HIGH	Delay time (second) [MSB]	16 bit (H word)	0	1
2 0	0x15	DELAY2_LOW	Delay time (second) [LSB]	16 bit (L word)	0	Read/Write
ау	0x16	HYSUP2_HIGH	Upper hysteresis value [MSB]	16 bit (H word)	0	1
Re	0x17	HYSUP2_LOW	Upper hysteresis value [LSB]	16 bit (L word)	0	1
	0x18	HYSDOWN2_HIGH	Lower hysteresis value [MSB]	16 bit (H word)	0	1
	0x19	HYSDOWN2_LOW	Lower hysteresis value [LSB]	16 bit (L word)	0	
	0x1A	OFFSET2_HIGH	Offset value [MSB]	16 bit (H word)	0	1
	0x1B	OFFSET2_LOW	Offset value [LSB]	16 bit (L word)	0	1
	0x1C	CONDITION_MODE2	Normally the state of the relay (0 = N.C. = Off 1 = N.O. = On)	16 bit (word)	0	
	0x1D	SET3A_HIGH	Set-3A value [MSB]	16 bit (H word)	0	
	0x1E	SET3A_LOW	Set-3A value [LSB]	16 bit (L word)	500	1
	0x1F	SET3B_HIGH	Set-3B value [MSB]	16 bit (H word)	0	
	0x20	SET3B_LOW	Set-3B value [LSB]	16 bit (L word)	800	
ut	0x21	MODE3	Function type (0=OFF, 1=Stand, 2=Band, 3=Catch, 4=Dual, 5=Periodic)	16 bit (word)	1	
utp	0x22	DELAY3_HIGH	Delay time (second) [MSB]	16 bit (H word)	0	1
elay 3 Output	0x23	DELAY3_LOW	Delay time (second) [LSB]	16 bit (L word)	0	Read/Write
ay	0x24	HYSUP3_HIGH	Upper hysteresis value [MSB]	16 bit (H word)	0	
Rel	0x25	HYSUP3_LOW	Upper hysteresis value [LSB]	16 bit (L word)	0	
	0x26	HYSDOWN3_HIGH	Lower hysteresis value [MSB]	16 bit (H word)	0	
	0x27	HYSDOWN3_LOW	Lower hysteresis value [LSB]	16 bit (L word)	0	
	0x28	OFFSET3_HIGH	Offset value [MSB]	16 bit (H word)	0	
	0x29	OFFSET3_LOW	Offset value [LSB]	16 bit (L word)	0	
	0x2A	CONDITION_MODE3	Normally the state of the relay (0 = N.C. = Off 1 = N.O. = On)	16 bit (word)	0	
	0x2B	SET4A_HIGH	Set-4A value [MSB]	16 bit (H word)	0	
	0x2C	SET4A_LOW	Set-4A value [LSB]	16 bit (L word)	800	_
	0x2D	SET4B_HIGH	Set-4B value [MSB]	16 bit (H word)	0	_
٠ ـ	0x2E	SET4B_LOW	Set-4B value [LSB]	16 bit (L word)	850	4
Relay 4 Output	0x2F	MODE4	Function type (0=OFF, 1=Stand, 2=Band, 3=Catch, 4=Dual, 5=Periodic)	16 bit (word)	1	Read/Write
Rela	0x30	DELAY4_HIGH	Delay time (second) [MSB]	16 bit (H word)	0	1
	0x31	DELAY4_LOW	Delay time (second) [LSB]	16 bit (L word)	0	
	0x32	HYSUP4_HIGH	Upper hysteresis value[MSB]	16 bit (H word)	0	
	0x33	HYSUP4_LOW	Upper hysteresis value [LSB]	16 bit (L word)	0	
	0x34	HYSDOWN4_HIGH	Lower hysteresis value [MSB]	16 bit (H word)	0	

HOLDING REGISTER ADDRESS TABLE							
	ding Register Idress (hex)	Parameter Name	Parameter Explanation	Count of Bit	Default Value	Read/Write	
Relay 4 Output	0x35	HYSDOWN4_LOW	Lower hysteresis value [LSB]	16 bit (L word)	0		
	0x36	OFFSET4_HIGH	Offset value [MSB]	16 bit (H word)	0		
	0x37	OFFSET4_LOW	Offset value [LSB]	16 bit (L word)	0	Read/Write	
	0x38	CONDITION_MODE4	Normally the state of the relay $(0 = N.C. = Off 1 = N.O. = On)$	16 bit (word)	0		

<sup>\*</sup> MSB (Most Significant Bit) or H word (HIGH): Represents the 16 bits which are significant for a 32-bit number.

<sup>\*</sup> For example to set the value of SET1A to 66.5, SET1A\_HIGH = 1000 (1.000d) and SET1A\_LOW = 964 (0.964d).

		<u>'</u>	, _ ,	<del>_</del>	,	,		
PUT3 ANALOG OUTPUT2 ANALOG OUTPUT1	0x39	ANALOG_OUTPUT1	1 = Analog output directly reflects the     value coming from the sensor.     0 = Analog output, manually specified in     percentage.		1			
	0x3A	ANALOG_OUTPUT1_SET	Specify analogue output as a manual percentage. Decimal points are always 2. For example; This value is 6500 (65.00d) since the analog output for 0-10 V is 6.5%.	16 bit (word)	0	Read/Write		
	0x3B	ANALOG_OUTPUT2	1 = Analog output directly reflects the value coming from the sensor. 0 = Analog output, manually specified in percentage		1			
	0x3C	ANALOG_OUTPUT2_SET	Specify analogue output as a manual percentage. Decimal points are always 2. For example; This value is 6500 (65.00d) since the analog output for 0-10 V is 6.5%.	16 bit (word)	0	Read/Write		
	0x3D	ANALOG_OUTPUT3	1 = Analog output directly reflects the value coming from the sensor. 0 = Analog output, manually specified in percentage		1			
ANALOG OUTPUT3	0x3E	ANALOG_OUTPUT3_SET	Specify analogue output as a manual percentage. Decimal points are always 2. For example; This value is 6500 (65.00d) since the analog output for 0-10 V is 6.5%.	16 bit (word)	0	Read/Write		
		Н	OLDING REGISTER ADDRESS TAB	LE				
Hol	Holding Register Parameter Name Parameter Explanation Count of Bit Read/Write							

Parameter Explanation

Count of Bit

Read/Write

Value

Parameter Name

Address (hex)

<sup>\*</sup> LSB (Least Significant Bit) or L word (LOW): refers to the 16 bits which are small for a 32-bit number.

<sup>\*</sup> For values to be entered with H word and L word, the function code Write Multiple Register (0x10) must be used and both values must be entered at any time. The decimal point value for these values is always 3.

	0x3F	UART PROTOCOL	Protocol selection (0=ASCII, 1=MB_RTU,		1	
	0,31	OART_FROTOCOL	2=MB_ASCII)		1 1 4 0 100	
	0x40	LIADT ADDECC	Address information for network		1	
	0.00	UART_ADRESS	connection (1 to 247)		1	
485			Baudrate (0=600, 1=1200, 2=2400,			
RS-	0x41	UART_BAUD	3=4800, 4=9600, 5=14400, 6=19200,		4	
8			7=38400, 8=57600, 9=115200)	16 bit (word)		Read/Write
232	0x42	UART_PARITY	Parity (0=None, 1=Odd, 2=Even)		0	
RS-:	0x43	UART_PERIOD	Period (1/ms cinsinden)		100	
	0x44	MODBUS_RAWDATA	It is used to send data from the connected MODBUS device to EPA (This feature is active in V3.3 and later versions)		-	

<sup>\*</sup> MSB (Most Significant Bit) or H word (HIGH): Represents the 16 bits which are significant for a 32-bit number.

- \* LSB (Least Significant Bit) or L word (LOW): refers to the 16 bits which are small for a 32-bit number.
- \* For values to be entered with H word and L word, the function code Write Multiple Register (0x10) must be used and both values must be entered at any time. The decimal point value for these values is always 3.
  - \* For example to set the value of SET1A to 25.5, SET1A\_HIGH = 0 (0d), SET1A\_LOW = 25500 (25.500d).
  - \*\* Analogue output set by parameter Analog\_Output1\_Set only operates when Analog\_Output1 = 0. When Analog\_Output1 = 1, the analog output is not in device control, the value from the sensor is transferred directly.

	analog output is not	in device control, the value from the sensor is	s transferred direc	tly.	
		NPUT REGISTER ADDRESS TABLE			
Input Register Address (hex)	Parameter Name	Parameter Explanation	Count of Bit	Default Value	Read/Write
0x00	ANALOG_RAW_VALUE	Unprocessed raw value from sensor		-	
0x01	DECIMAL_POINTS	Decimal point location on the screen display (0=A, 1=A.A, 2=A.AA, 3=A.AAA 4=A.AAAA)		1	
0x02	PROCESS_VALUE	Current value displayed on device screen	16 bit (word)	-	Read-only
0x03	VALLEY_VALUE	The lowest value read since the device was turned on		-	
0x04	PEAK_VALUE	The highest value read since the device was turned on		-	
0x05	DIGITAL_IOS	Status of External Tare Module (4.bit), status of 1st and 2nd relays (0. and 1.bit) [00000 = All Inactive, 10011 = All Active]	16 bit (word)	00000	Read-only
0x06	TARE_STATUS	Process Value indicates whether the value is tare or not. 0 = no tare, 1 = tare		0	
Function Code	<b>Definitons</b>				
Read Coil		0x01			-
Read Holding Re	gister	0x03			
Read Input Regis		0x04	A		
Write Single Coil		0x05			
Write Single Reg	ister	0x06		1	1-
Write Multiple Coils		0x0f			K
Write Multiple Register		0x10			